

**IN THE SPECIFICATION:**

**Please amend the paragraph beginning at page 6, line 21 as follows:**

A<sup>2</sup>

Referring to Fig. 1 in addition to Fig. 1a, where a particular angle of rotation of the display about axis Y is known to or determined by the control unit 52, the control unit 52 is programmed to output corresponding control signals to the stepper motor 36. The control signals cause the stepper motor 52 36 (and, consequently, the display 24 by virtue of its attachment to vertical support 40) to rotate its drive shaft through the particular angle. The drive shaft of the stepper motor (which is also parallel to axis Y) has a reference position where the normal vector  $N_x$  of the display screen is parallel with axis X as described above. Control unit 52 keeps track of the rotation of the drive shaft and the display with respect to axis X, for example, by keeping track of the rotation of the drive shaft of stepper motor 36 due to the control signals sent by the control unit 52, or by a feedback signal to the control unit 52 of the rotation position.

**Please amend the paragraph beginning at page 9, line 11 as follows:**

A<sup>3</sup>

Image recognition software is loaded in control unit 52 and is used by a processor therein to process the images received from the camera 52 48. Depending on the camera, the images may be a series of discrete images or video frames. The images as processed by the control unit 52 may be, for example, the intensity data captured by an array of pixels in a CCD array of a digital camera or digital video camera and transferred to the control unit 52. The components, including memory, of the control unit 52 used for image recognition may be separate or may be shared with the other functions of the display 24.